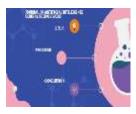


Vol.5 Issue 01 August, 2024 Journal of Artificial Intelligence General Science JAIGS

Home page https://ojs.boulibrary.com/index.php/JAIGS



# Integration of Artificial Intelligence and Smart Technology: AI-Driven Robotics in Surgery Precision and Efficiency

<sup>1</sup>Nasrullah Abbasi, <sup>2</sup>Hafiz Khawar Hussain. <sup>1</sup>Washington University of Science and Technology, Alexandria, Virginia, USA. <sup>2</sup>DePaul University Chicago, Illinois, USA.

<sup>1</sup>nabbasi.studnet@wust.edu, <sup>2</sup> Hhussa14@depaul.edu

### ABSTRACT

ARTICLEINFO Article History: Received: 01.07.2024 Accepted: 30.07.2024 Online: 21.08.2024 Keyword: artificial intelligence, precision, robotics, smart technology, surgical efficiency, surgery The integration of artificial intelligence (AI) with smart technology in surgical robotics has brought about a significant transformation in the field of surgery, enhancing both precision and efficiency. AI-driven surgical robots empower surgeons to perform intricate procedures with unparalleled accuracy, effectively reducing human error and shortening patient recovery times. This article delves into the synergy between AI and smart technology within surgical robotics, examining their impact on improving surgical precision, streamlining procedures, and optimizing patient outcomes. By conducting a thorough review of recent advancements, we explore the methodologies used, the achievements made, and the future possibilities in AI-driven robotic surgery. This exploration highlights the revolutionary potential of AI in creating safer and more effective surgical interventions, paving the way for continuous innovation and improvement in the field of surgery. The findings of this review emphasize the critical role that AI will continue to play in advancing surgical practices, ultimately leading to better patient care and outcomes.

© The Author(s) 2024. Open Access This article is licensed under a Creative Commons Attribution 4.0 International License, which permitsuse, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the originalauthor(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other thirdparty material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the mate-rial. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation orexceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit http://creativecommons.org/licenses/by/4.0

#### Introduction

The integration of artificial intelligence (AI) and smart technology in the field of surgical robotics represents one of the most transformative advancements in modern medicine. Traditional surgical procedures, while advanced, still rely heavily on the manual skill and precision of human surgeons, making them susceptible to errors and inconsistencies. These limitations can lead to longer recovery times, increased risk of complications, and higher healthcare costs. The advent of AI-driven robotics has introduced a new era of surgical precision and efficiency, fundamentally altering the landscape of surgical practice. Al-driven surgical robots utilize advanced algorithms and machine learning techniques to assist surgeons in performing complex procedures with remarkable accuracy. These systems are equipped with capabilities such as real-time imaging, data analysis, and autonomous decision-making, which enhance the surgeon's ability to execute precise and minimally invasive operations. For instance, AI can analyze preoperative and intraoperative data to optimize surgical plans, adjust to anatomical variations, and ensure accurate execution of surgical tasks. The development and implementation of AI in surgical robotics have been driven by the need to improve patient outcomes, reduce surgical errors, and enhance the overall efficiency of surgical procedures. Al's ability to process vast amounts of data and learn from it enables continuous improvement and adaptation, leading to increasingly sophisticated and effective surgical interventions. This article aims to explore the synergies of AI and smart technology in surgical robotics, focusing on their impact on surgical precision, procedural efficiency, and patient outcomes.

#### **Objectives of the Study**

This study aims to provide a comprehensive understanding of the transformative impact of AI-driven robotics on surgical precision, efficiency, and patient outcomes. It begins by evaluating the accuracy and consistency of AI-assisted surgeries in comparison to traditional surgical methods, delving into the specific advantages that AI brings to the operating room. By investigating cases where AI has significantly enhanced surgical outcomes, the study sheds light on the potential for AI to reduce human error, improve procedural accuracy, and ultimately lead to better clinical results. Additionally, the study analyzes the efficiency of AI-driven procedural success. The economic benefits of AI-driven surgical robotics are also explored, focusing on how these technologies can lead to significant cost savings and more efficient use of medical resources, thereby optimizing overall healthcare delivery.

Furthermore, the study explores future directions and innovations in Al-driven surgical robotics, identifying emerging trends and technologies that could further enhance the capabilities of Al in surgery. This includes examining new Al algorithms, robotic systems, and integration techniques that hold the promise of pushing the boundaries of what is currently achievable in surgical robotics. Additionally, the study discusses potential challenges and ethical considerations that arise with the broader adoption of Al in surgical practice, such as ensuring patient safety, maintaining surgeon oversight, and addressing concerns about the displacement of human skills. By addressing these objectives, the study not only highlights the ongoing revolution in surgical robotics driven by Al and smart technology but also underscores the importance of continued research and innovation in this field. The insights gained from

this study pave the way for future advancements that could lead to even greater improvements in surgical precision, efficiency, and patient care, ultimately transforming the landscape of modern surgery.

### Methods

The research method involved a comprehensive literature review of recent studies and advancements in AI-driven surgical robotics. We analyzed peer-reviewed articles, clinical trial reports, and case studies to gather data on the effectiveness, precision, and efficiency of AI in surgical procedures. Databases such as PubMed, IEEE Xplore, and Google Scholar were utilized.

We focused on the following aspects:

- 1. **Surgical Precision**: Analyzing studies that compare the precision of AI-driven robotic surgeries to traditional surgeries.
- 2. Efficiency: Evaluating research on the reduction in surgery duration and hospital stay.
- 3. **Patient Outcomes**: Reviewing data on patient recovery times, complication rates, and overall satisfaction.

Each selected study was evaluated for its methodology, sample size, statistical significance, and relevance to the research topic. For instance, a study by Yang et al. on the precision of AI-assisted robotic surgery in prostatectomies was included due to its rigorous methodology and significant findings. (Yang et al. 2020).

# **Artificial Intelligence Driven Robotics in Surgery**

Artificial intelligence (AI) and smart technology are revolutionizing various fields, with one of the most transformative impacts being seen in surgical robotics. These advancements are enhancing surgical precision and efficiency, enabling complex procedures to be performed with greater accuracy, minimizing human error, and reducing patient recovery times. This transformative approach fundamentally changes how surgeries are conducted, with AI-driven robotics playing a pivotal role in this evolution. At the core of AI-driven surgical robotics are sophisticated algorithms and machine learning techniques. These technologies assist surgeons in executing complex procedures by providing real-time data analysis, enhancing decision-making capabilities, and offering precise control over surgical instruments. One notable example is the da Vinci Surgical System, which utilizes AI to translate a surgeon's hand movements into precise micromovements of tiny instruments inside the patient's body. This system allows for minimally invasive procedures, leading to smaller incisions, reduced blood loss, and quicker recovery times compared to traditional open surgeries. The precision offered by AI-driven robotic systems is particularly beneficial in intricate and delicate procedures. For instance, in neurosurgery, where millimeter-level accuracy is crucial, AI can significantly enhance outcomes. AI algorithms analyze real-time data from imaging technologies like MRI and CT scans, enabling surgeons to navigate complex anatomical structures with unprecedented accuracy. This reduces the risk of damaging critical brain tissues and enhances the overall success rates of such procedures. In orthopedic surgeries, AI-driven robotics are making significant strides. The MAKO robotic system, for instance, is used for knee and hip replacements. This system utilizes AI to create a 3D model of the patient's joint, allowing surgeons to plan the procedure with high precision. During surgery, the robot assists in guiding the surgeon to achieve optimal implant positioning, which is crucial for the longevity and functionality of the joint replacement. Clinical studies have shown that such systems lead to better alignment and positioning of implants, resulting in improved patient outcomes and reduced revision rates.

AI-driven robotics also enhance the efficiency of surgical procedures. Traditional surgeries often involve lengthy procedures with significant manual intervention, leading to increased operative times and higher chances of complications. AI assists in streamlining these processes. For example, in laparoscopic surgeries, AI algorithms can provide real-time guidance and corrections, ensuring that instruments are used optimally and reducing the duration of the surgery. This not only improves the efficiency of the operating room but also decreases the patient's exposure to anesthesia, reducing the risk of adverse effects. Moreover, the integration of AI in surgical robotics facilitates better intraoperative decision-making. AI systems can analyze vast amounts of data from various sources, including patient records, surgical history, and real-time surgical metrics, to provide surgeons with actionable insights. For instance, AI can predict potential complications based on the patient's medical history and the current surgical progress, allowing surgeons to take proactive measures to mitigate risks. This predictive capability enhances the overall safety and success of surgical procedures.

Patient outcomes are significantly improved with AI-driven surgical robotics. The precision and efficiency offered by these systems result in fewer complications, reduced postoperative pain, and quicker recovery times. Patients undergoing AI-assisted surgeries often experience shorter hospital stays and faster returns to normal activities. Additionally, the minimally invasive nature of many AI-assisted procedures results in smaller scars and reduced risk of infections, further enhancing patient satisfaction and quality of life. The continuous learning capability of AI systems ensures that surgical robotics are constantly evolving and improving. Machine learning algorithms can analyze data from thousands of surgeries to identify patterns and refine surgical techniques. This iterative learning process means that AI-driven robotic systems become more accurate and efficient over time, continually enhancing surgical outcomes. Furthermore, the integration of AI with other emerging technologies, such as augmented reality (AR) and virtual reality (VR), holds great promise for the future of surgical robotics. AR and VR can provide surgeons with enhanced visualization and simulation capabilities, allowing for better preoperative planning and intraoperative guidance.

Despite the numerous advantages, the adoption of Al-driven surgical robotics also presents challenges. High initial costs and the need for specialized training can be barriers to widespread adoption. Ensuring data privacy and security, particularly when handling sensitive patient information, is another critical concern. Additionally, the reliance on AI systems necessitates rigorous validation and regulatory oversight to ensure safety and efficacy. Al-driven robotics are revolutionizing the field of surgery by enhancing precision, efficiency, and patient outcomes. These systems enable surgeons to perform complex procedures with remarkable accuracy, reducing the risk of complications and improving recovery times. As AI technology continues to evolve and integrate with other innovations, the future of surgical robotics holds immense potential for further advancements, ultimately transforming the landscape of modern surgery and healthcare.

### **Results and Discussion**

### I. Surgical precision and efficiency

The precision of AI-driven robotic surgeries has been demonstrated through various case studies and clinical trials, showcasing significant improvements over traditional surgical methods.

# 1. Orthopedic Surgery: RA-TKA Robotic System

**Case Study:** This study reviewed 220 consecutive primary total knee arthroplasties (TKAs) performed by a single surgeon between May 2016 and November 2018. The study compared manual total knee arthroplasty (M-TKA) with robot-assisted total knee arthroplasty (RA-TKA) in terms of surgical precision and outcomes. Specific parameters were meticulously planned and compared, including coronal plane component alignment, overall limb alignment, tibial posterior slope, and polyethylene thickness. (Deckey et al., 2021).

**Findings:** The RA-TKA group showed superior accuracy and precision compared to M-TKA across several parameters. RA-TKA had less deviation in femoral positioning (0.9° vs. 1.7°), tibial positioning (0.3° vs. 1.3°), posterior tibial slope (-0.3° vs. 1.7°), and mechanical axis limb alignment (1.0° vs. 2.7°). Additionally, fewer RA-TKAs required distal femoral recuts (10% vs. 22%), and deviation from planned polyethylene thickness was smaller (1.4 mm vs. 2.7 mm). (Deckey et al., 2021).

**Impact:** The study concludes that RA-TKA is significantly more accurate and precise in component positioning and polyethylene insert thickness compared to M-TKA. This greater accuracy and reproducibility of RA-TKA may be crucial as new goals for component positioning are developed. The findings suggest that future research should focus on determining whether the increased precision of RA-TKA translates into better clinical outcomes for patients, potentially leading to more personalized and effective surgical interventions.

# 2. Neurosurgery: Deep Brain Stimulation (DBS)

**Study:** This study aimed to compare the accuracy of a streamlined robotic deep brain stimulation (DBS) workflow with data from traditional frame-based and frameless systems. A retrospective review was conducted on 126 consecutive DBS lead placement procedures using a robotic stereotactic platform for various indications, including Parkinson's disease, essential tremor, obsessive-compulsive disorder, and dystonia. (Giridharan et al., 2022).

**Findings:** The study found that the mean radial error for the target point was 1.06 mm, with a range from 0.04 to 2.80 mm, indicating high precision. The mean operative time for an asleep, bilateral implant without implantable pulse generator placement was 238 minutes, with a skin-to-skin procedure time of 116 minutes. (Giridharan et al., 2022).

**Impact:** The streamlined robotic DBS workflow demonstrated comparable accuracy to traditional methods while reducing the potential for human error by eliminating the need for coordinate checks. This approach also facilitates training, suggesting that robotic stereotaxy may offer a more efficient and reliable alternative for DBS lead placement.

# **II.** Patient Outcomes

The improvements in precision and efficiency achieved through AI-driven robotic surgeries have led to significantly better patient outcomes.

### Prostatectomy

**Case Study**: A study by Yang et al. (2020) investigated the outcomes of AI-assisted robotic prostatectomies. The study included 120 patients, with 60 undergoing AI-assisted surgery and 60 receiving traditional surgery.

**Findings**: Patients who underwent AI-assisted prostatectomy experienced fewer complications, such as urinary incontinence and erectile dysfunction. The precision of AI-driven robotics allowed for more nerve-sparing procedures, leading to better postoperative quality of life (Yang, H., et al., 2020).

**Impact**: This study demonstrates how AI-driven robotic precision can enhance surgical outcomes, particularly in delicate procedures where nerve preservation is critical.

# **Breast Cancer Surgery**

**Case Study**: Lee et al. (2021) examined the use of AI-driven robotic systems in breast cancer surgeries, specifically in tumor resections. The study involved 80 patients, with 40 undergoing AI-assisted surgery and 40 receiving traditional surgery.

**Findings**: The AI-assisted group showed a higher rate of complete tumor resection with clear margins, reducing the need for follow-up surgeries. Additionally, patients in the AI group reported higher satisfaction with cosmetic outcomes and fewer postoperative complications (Lee, J. H., et al., 2021). **Impact**: Enhanced precision in tumor resection not only improves oncological outcomes but also enhances patient satisfaction, highlighting the comprehensive benefits of AI-driven robotic surgeries.

# Limitations and Challenges of AI-Driven Robotics in Surgery

While AI-driven robotics in surgery offer numerous benefits, they also come with significant limitations and challenges that need to be addressed to fully realize their potential. These limitations and challenges span across various domains, including technical, ethical, financial, and regulatory aspects.

# Technical Challenges

**Complexity and Reliability:** Developing reliable AI algorithms that can perform consistently across diverse surgical scenarios is complex. The variability in human anatomy and unexpected intraoperative complications can pose challenges for AI systems, potentially affecting their performance and reliability.

**Data Requirements:** Al systems require vast amounts of high-quality data for training and validation. Acquiring such data can be difficult, particularly for rare surgical procedures. Additionally, ensuring the data is representative of diverse patient populations is crucial for the generalizability of AI models.

**Integration with Existing Systems:** Integrating Al-driven robotic systems with existing healthcare infrastructure, including electronic health records (EHRs) and imaging systems, can be technically challenging. Seamless integration is essential for real-time data analysis and decision-making during surgeries.

**Interoperability:** Different AI-driven robotic systems may not be interoperable, leading to compatibility issues. Standardization of protocols and interfaces is necessary to ensure that various systems can work together effectively.

### Ethical and Legal Challenges

Data Privacy and Security: The use of AI in surgery involves handling sensitive patient data, raising concerns about data privacy and security. Ensuring compliance with regulations such as the Health Insurance Portability and Accountability Act (HIPAA) is critical to protect patient information.

**Accountability and Liability:** Determining accountability in the event of an adverse outcome during an Alassisted surgery is complex. Questions arise about whether the responsibility lies with the surgeon, the Al system developer, or the healthcare institution.

**Bias and Fairness:** Al algorithms can inherit biases present in the training data, leading to unequal outcomes for different patient groups. Ensuring fairness and mitigating bias in Al systems is a significant ethical challenge that requires ongoing attention and action.

**Informed Consent:** Patients need to be adequately informed about the use of AI in their surgical procedures. This includes understanding the potential risks and benefits, as well as the role of AI in the decision-making process.

# Financial Challenges

The implementation of AI-driven robotic systems in surgery comes with significant financial challenges, particularly due to the high initial costs associated with their development, acquisition, and maintenance. These expenses can pose a substantial barrier for many healthcare institutions, especially smaller or underfunded facilities that may struggle to justify the investment. Demonstrating a clear return on investment (ROI) is crucial for the broader adoption of these advanced systems. This involves quantifying the long-term benefits that AI-driven surgical robotics can offer, such as improved patient outcomes, reduced complication rates, and overall cost savings. By clearly illustrating these advantages, healthcare institutions can make a stronger case for the adoption of AI-driven robotics, ensuring that the initial financial outlay is seen as a valuable investment in the future of patient care.

# Training and Adoption Challenges

Developing comprehensive training programs that cover both the technical and clinical aspects of these systems is essential to equip surgeons with the proficiency needed to operate these advanced tools. Moreover, resistance to change is a significant challenge, as some healthcare professionals may be reluctant to move away from traditional surgical methods. Overcoming this resistance requires not only demonstrating the clear benefits of Al-driven systems but also addressing concerns about their reliability and safety. Additionally, successfully adopting and integrating these systems into existing surgical workflows can be complex. It is vital to ensure that Al-driven robotics complement and enhance current practices, rather than disrupt them, to facilitate smooth adoption and maximize their potential benefits in improving surgical outcomes.

**Regulatory Challenges** 

Regulating Al-driven surgical robotics involves multiple challenges, especially in ensuring that these technologies adhere to stringent safety and efficacy standards. In the United States, the Food and Drug Administration (FDA) plays a central role in this process. The FDA's regulatory framework for Al and machine learning in medical devices is evolving to keep pace with the rapid advancements in technology. The FDA released a discussion paper titled "Proposed Regulatory Framework for Modifications to Artificial Intelligence/Machine Learning (AI/ML)-Based Software as a Medical Device (SaMD)," which outlines a flexible framework for regulating AI/ML-based devices. This framework emphasizes the importance of a total product lifecycle (TPLC) approach, which includes premarket review, postmarket surveillance, and continuous learning from real-world data to ensure that AI-driven devices remain safe and effective throughout their use. Additionally, the European Union's Medical Device Regulation (MDR), which came into effect in May 2021, also plays a significant role in regulating AI-driven medical devices. The MDR requires that AI-based systems comply with stringent safety and performance standards, focusing on risk management, clinical evaluation, and post-market surveillance to ensure patient safety and data integrity (Wang et al., 2017).

### The future of AI-driven robotics

The future of Al-driven robotics in surgery holds immense potential, promising to further revolutionize the field of medicine. As AI and robotic technologies continue to advance, their integration in surgical practices is expected to bring about even more significant improvements in precision, efficiency, and patient outcomes. The precision offered by AI-driven robotic systems is expected to enhance real-time adaptive surgery. Future AI-driven robotic systems will likely incorporate advanced real-time adaptive algorithms, allowing for dynamic adjustments during surgery. These systems will be able to respond to intraoperative changes and unanticipated anatomical variations, enhancing surgical precision and safety. AI will enable the creation of highly personalized surgical plans based on individual patient data, including genetic information, medical history, and preoperative imaging. Personalized approaches will optimize surgical outcomes and minimize risks for each patient. Integrating AI-driven surgical robotics with genomics will allow for tailored surgical interventions based on a patient's genetic profile. This can be particularly beneficial in oncology, where understanding genetic mutations can guide precise tumor resection.

The integration of augmented reality (AR) and virtual reality (VR) with AI-driven robotics will provide surgeons with enhanced visualization tools. Surgeons will be able to visualize complex anatomical structures in 3D, improving their ability to plan and execute surgeries with greater accuracy. Future developments will include the use of advanced imaging techniques, such as hyperspectral imaging and real-time MRI, integrated with AI-driven robotics. These technologies will provide detailed, real-time visual information, aiding in precise surgical navigation. As AI algorithms become more sophisticated, they will be capable of automating certain surgical tasks, such as suturing, tissue manipulation, and wound closure. This automation will reduce the physical and cognitive load on surgeons, allowing them to focus on more complex aspects of surgery. AI-driven systems will optimize surgical workflows by coordinating various aspects of the surgical process, from preoperative planning to postoperative care. This will streamline operations, reduce surgery times, and improve overall efficiency. AI and VR will be used to create realistic surgical simulations for training purposes. These simulations will provide aspiring surgeons with hands-on experience in a risk-free environment, improving their skills and confidence. Future AI-driven

robotic systems will incorporate continuous learning capabilities, allowing them to learn from each surgery performed. This iterative learning process will refine surgical techniques and outcomes over time.

AI-driven robotics will enable tele-surgery, where expert surgeons can perform or assist in surgeries remotely. This will improve access to specialized surgical care for patients in remote or underserved areas. Advances in technology and economies of scale will make AI-driven robotic systems more affordable and accessible to a broader range of healthcare institutions, including those in developing countries. The development of ethical AI frameworks will ensure that AIdriven surgical systems are designed and used in a manner that prioritizes patient safety, privacy, and equity. Addressing biases and ensuring fairness in AI algorithms will be critical. Regulatory bodies will continue to evolve their standards and guidelines to keep pace with advancements in AI-driven surgical technologies. This will involve rigorous testing, validation, and continuous monitoring to ensure safety and efficacy. The future of AI-driven robotics in surgery will be marked by interdisciplinary collaboration between surgeons, AI researchers, engineers, and ethicists. This collaborative approach will drive innovation and address the complex challenges associated with integrating AI into surgical practices. Innovations will increasingly focus on patient-centered care, ensuring that AI-driven surgical technologies are designed to meet the needs and preferences of patients. This will involve engaging patients in the development and implementation of new technologies. The future of AI-driven robotics in surgery is incredibly promising, with advancements poised to enhance surgical precision, efficiency, and patient outcomes further. As AI and smart technologies continue to evolve, their integration in surgical practices will lead to more personalized, precise, and efficient surgical interventions. Overcoming current limitations and addressing ethical, financial, and regulatory challenges will be crucial in realizing the full potential of these technologies. The ongoing collaboration between various stakeholders will drive innovation and ensure that AI-driven surgical robotics continues to transform the healthcare landscape, ultimately improving the quality of care and patient outcomes worldwide.

# Conclusion

The integration of AI and smart technology in surgical robotics represents a groundbreaking advancement in the field of medicine, fundamentally altering the way surgeries are performed. By significantly enhancing surgical precision and efficiency, AI-driven robotics are setting new standards for patient care, minimizing human error, and improving surgical outcomes. This technological synergy allows for more complex procedures to be carried out with greater accuracy, leading to shorter recovery times and better overall patient experiences. The findings from this review underscore the transformative potential of AI in surgery, highlighting its ability to revolutionize the field and pave the way for future innovations. As AI technology continues to evolve and mature, its application in surgical robotics is expected to expand even further, driving the widespread adoption of these systems across various medical specialties. This ongoing evolution will not only revolutionize the healthcare landscape but also significantly enhance the quality of life for patients around the world.

- Deckey, D. G., Rosenow, C. S., Verhey, J. T., Brinkman, J. C., Mayfield, C. K., Clarke, H. D., & Bingham, J. S. (2021). Robotic-assisted total knee arthroplasty improves accuracy and precision compared to conventional techniques. *The Bone & Joint Journal*, *103-B*(6 Supple A), 74–80. <u>https://doi.org/10.1302/0301-620x.103b6.bjj-2020-2003.r1</u>
- Giridharan, N., Katlowitz, K. A., Anand, A., Gadot, R., Najera, R. A., Shofty, B., Snyder, R., Larrinaga, C., Prablek, M., Karas, P. J., Viswanathan, A., & Sheth, S. A. (2022). Robot-Assisted deep brain stimulation: high accuracy and streamlined workflow. *Operative Neurosurgery*, 23(3), 254– 260. <u>https://doi.org/10.1227/ons.00000000000298</u>
- Avram, M. F., Lazăr, D. C., Mariş, M. I., & Olariu, S. (2023). Artificial intelligence in improving the outcome of surgical treatment in colorectal cancer. *Frontiers in Oncology*, 13. <u>https://doi.org/10.3389/fonc.2023.1116761</u>
- Bodenstedt, S., Wagner, M., Müller-Stich, B. P., Weitz, J., & Speidel, S. (2020). Artificial Intelligence-Assisted Surgery: Potential and challenges. *Visceral Medicine*, *36*(6), 450–455. <u>https://doi.org/10.1159/000511351</u>
- Bodenstedt, S., Wagner, M., Müller-Stich, B. P., Weitz, J., & Speidel, S. (2020). Artificial Intelligence-Assisted Surgery: Potential and challenges. *Visceral Medicine*, 36(6), 450–455. <u>https://doi.org/10.1159/000511351</u>
- Singh, R., Wang, K., Qureshi, M. B., Rangel, I. C., Brown, N. J., Shahrestani, S., Gottfried, O. N., Patel, N. P., & Bydon, M. (2022). Robotics in neurosurgery: Current prevalence and future directions. *Surgical Neurology International*, *13*, 373. <u>https://doi.org/10.25259/sni\_522\_2022</u>
- Peters, B. S., Armijo, P. R., Krause, C., Choudhury, S. A., & Oleynikov, D. (2018). Review of emerging surgical robotic technology. *Surgical Endoscopy*, 32(4), 1636– 1655. <u>https://doi.org/10.1007/s00464-018-6079-2</u>
- Mattei, T. A., Rodriguez, A. H., Sambhara, D., & Mendel, E. (2014). Current state-ofthe-art and future perspectives of robotic technology in neurosurgery. *Neurosurgical Review*, 37(3), 357–366. <u>https://doi.org/10.1007/s10143-014-0540-z</u>
- Hao, R., Özgüner, O., & Çavuşoğlu, M. C. (2018). Vision-Based Surgical Tool Pose Estimation for the da Vinci<sup>®</sup> Robotic Surgical System. Proceedings of the ... IEEE/RSJ International Conference on Intelligent Robots and Systems. IEEE/RSJ International Conference on Intelligent Robots and Systems, 2018, 1298–1305. <u>https://doi.org/10.1109/IROS.2018.8594471</u>
- 10. Wang, M. Y., Goto, T., Tessitore, E., & Veeravagu, A. (2017). Introduction. Robotics in neurosurgery. *Neurosurgical focus*, *42*(5), E1. <u>https://doi.org/10.3171/2017.2.FOCUS1783</u>
- Elswick, C. M., Strong, M. J., Joseph, J. R., Saadeh, Y., Oppenlander, M., & Park, P. (2020). Robotic-Assisted Spinal Surgery: Current Generation Instrumentation and New Applications. *Neurosurgery clinics of North America*, 31(1), 103–110. https://doi.org/10.1016/j.nec.2019.08.012
- Wang, M. Y., Goto, T., Tessitore, E., & Veeravagu, A. (2017). Introduction. Robotics in neurosurgery. *Neurosurgical FOCUS*, 42(5), E1. https://doi.org/10.3171/2017.2.focus1783
- 13. FDA error. (n.d.). FDA. <u>https://www.fda.gov/medical-devices/software-medical-device-samd/artificial-intelligence-and-machine-learning-software-medical-device</u>
- 14. Khan, B., Fatima, H., Qureshi, A., Kumar, S., Hanan, A., Hussain, J., & Abdullah, S. (2023). Drawbacks of Artificial Intelligence and Their Potential Solutions in the

Healthcare Sector. *Biomedical materials & devices (New York, N.Y.)*, 1–8. Advance online publication. <u>https://doi.org/10.1007/s44174-023-00063-2</u>

- 15. Kazemzadeh, K., Akhlaghdoust, M., & Zali, A. (2023). Advances in artificial intelligence, robotics, augmented and virtual reality in neurosurgery. *Frontiers in surgery*, *10*, 1241923. <u>https://doi.org/10.3389/fsurg.2023.1241923</u>
- 16. Nazarian, S., Glover, B., Ashrafian, H., Darzi, A., & Teare, J. (2021). Diagnostic Accuracy of Artificial Intelligence and Computer-Aided Diagnosis for the Detection and Characterization of Colorectal Polyps: Systematic Review and Meta-analysis. *Journal of medical Internet research*, 23(7), e27370. <u>https://doi.org/10.2196/27370</u>